

However, nothing prevents the use of other, intermediate l_c values as well, following the suggestions mentioned above, as this will most often not have a significant effect on the accuracy of the achieved curvature of the track axis. In this respect, the moving chord method is very flexible.

It is also possible to adopt a different (i.e. shorter) chord when determining the curvature along the length of the transition curve than is the case for a circular curve. During the analysis for the test section $V = 80$ km/h, a chord of $l_c = 30$ m would be most favourable for the identification of the curvature of the circular curve and a chord of $l_c = 20$ m for the identification of the curvature of the transition curve. For the test section $V = 120$ km/h, a chord $l_c = 40$ m for the circular curve and $l_c = 30$ m for the transition curves would be suitable, while the appropriateness of using a chord $l_c = 40$ m for the identification of transition curves on the test section $V = 120$ km/h should be considered (the curvature of the circular curve must be determined here using a chord $l_c = 50$ m).

7. Conclusions

The basis for determining the position of straight sections of the railway track and sections located in a curve, as well as for determining the corresponding geometric parameters, is the knowledge of the curvature of the track axis. The works [23–25] present the concept of a new method for determining curvature (called the “moving chord method”) and its verification on an unambiguously defined elementary geometric layout of tracks.

The papers [26, 30, 31] discuss the procedure for estimating the curvature of a track axis by the moving chord method using Cartesian coordinates obtained by direct measurements carried out. It was shown that values of circular curve radius and lengths of transition curves, as well as the location of so-called segmentation points (i.e. boundary points between straight sections, transition curves and circular curves) can be determined from the curvature diagram.

This article focuses on the issue of selecting the chord length that will be most beneficial in a particular situation. Although for the model systems, as shown in the work [24], the effect of the applied chord length on the determined curvature values turned out to be insignificant, in the operated railway track, due to track deformations and measurement error, the situation may differ significantly. This is evidenced, for example, by the irregular curvature diagrams shown in the paper [31]. The study analysed three test geometric layouts adapted to the speeds of 80 km/h, 120 km/h and 160 km/h (the radii of circular arcs determined as a result of the curvature esti-

mation performed were approximately 410 m, 880 m and 1480 m, respectively). The lengths of the moving chord in the range of 10÷50 m were considered.

On the basis of the conducted analysis, it was unequivocally demonstrated that the chord length used to determine the curvature in the railway track in service should depend on the value of the radius of the circular curve. The virtual chord should not be too short; for example, using a chord length of $l_c = 10$ m is not a reasonable solution. A chord $l_c = 20$ m may also be of little use for large circular curve radii; in such cases, a chord $l_c = 50$ m should be considered. Indicative lengths of l_c have been suggested, depending on the range of values of R_{CA} , but nothing prevents the use of other, intermediate values of l_c , as this will usually not have a significant impact on the accuracy of the achieved curvature of the track axis. In this respect, the moving chord method is very flexible. It is also possible to adopt a different (i.e. slightly shorter) chord when determining the curvature along the length of the transition curve than is the case for a circular curve. Often, the position and length of the transition curve can be determined more accurately from the curvature diagram obtained using a shorter chord.

The issues presented in the article, concerning the adaptation of the moving chord method to the adopted measurement procedure and the use of the obtained curvature diagram, provide a suitable application basis for the described method. Implementation of the presented procedure should significantly improve the process of identification of geometric layouts of the track in the horizontal plane.

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